

REMARKS/ARGUMENTS

The Applicant respectfully requests entry of this amendment, consideration of this response and withdrawal of the outstanding rejection.

By this amendment, claims have been canceled or amended to more clearly articulate the invention in response to the final office action.

The Examiner is to be thanked for the explanation of his interpretation of claim language. While the Applicant respectfully disagrees with the logic of the Examiner's position and the appropriateness of the cited art, as hereinafter noted, the Applicant also feels compelled to explain the theory behind the invention so that the claim language is considered in proper context.

The Examiner has stated that real time processing is a subjective term which in this instance the Examiner is interpreting to mean "a process being done before a deadline to prevent bottlenecks." The Examiner refers to a statement in Chin reciting that peak performance processing of the system therein is 40 billion operations per second, which the Examiner has interpreted as real-time processing. The Applicant offers a more precise definition and herewith respectfully points out that the interpretation of Chin as real time is fundamentally flawed, even by the Examiner's definition. A real-time process is one in which computation is during the actual time that the related physical process transpires in order that results of the computation can be used in guiding the physical process. (*IEEE Standard Dictionary of Electrical and Electronic Terms*) Real-time systems are those that guarantee that the system will respond in a predetermined amount of time. (*The Electrical Engineering Handbook* Sect. 96.6)

Thus, a processor or processor set may be slow or fast, so long as it guarantees that its processing invariably yields a solution to a problem before the processing system enters a non-reversible catastrophic state. Chin does not guarantee such a solution, a solution to a problem in interaction with the physical world. Thus, the Applicant submits that the term "real time" has not been given proper patentable weight in the claims. Moreover, Chin is a non-enabling disclosure, and the Applicant can supply reports thereof if required. Such reports would

disclose that it is generally known in the art that Chin and systems of its ilk do not work as asserted.

Referring to the invention as generally claimed and now in claims 1 and 10 as more specifically amended, namely a system and method that provide image analysis in a real-time (i.e., guaranteed-solution) physical environment, the claims recite three distinctly different layers of processing that solve at least three distinctly different task sets, now even more specifically defined. Layer One is a processing layer that solves the per-pixel processing tasks, such as sharpening the image, enhancing contrast and color separation, and enhancing gradients and thereby improving the ability of the next layer to distinguish objects.

Layer Two sits on top of Layer One and works in conjunction with Layer One. That means that Layer One and Layer Two must both be present simultaneously for the system to provide Layer Two results. Layer Two finds object perimeters and therefore is referred to as object-dependent and pixel-independent. It determines object perimeters to find object boundaries, and it does not necessarily identify objects. It determines static and dynamic object features, such as linear and non-linear motion parameters of all objects in the field of vision. Results from Layer Two are used by Layer Three, meaning that Layer One, Layer Two and Layer Three must be present to constitute a complete solution to real-time image analysis. Layer Three takes the Layer Two results (and of course implicitly Layer One results) and uses them. Examples of Layer Three processing is computation of data to present results, tracing back the objects' motion to its origin, or predicting the future path or trajectory of the objects in the field of vision. Other results can be derived from the extracted data in Layers One and Two, but all results can be used in Layer three to present, display or further compute these data sets. Layer Three processing can occur in any general-purpose single-core or multi-core RISC or CISC processor. As now more specifically recited in claim 1 and as due to the demands of real-time processing, Layer One is an MPP SIMD, and Layer Two is an SMP-type matrix multiplication processor architecture combined with an SMP-type Fast Fourier Transform processor architecture (including for example a DFT architecture). Any layer on top of Layer Three may be a single-core or multi-core RISC or CISC processor architecture, with an appropriate reliable

operating system. Layers One and Two do not need a general purpose operating system since their real-time requirements dominate the needs, and not the ability to manage resources.

By this response, the Applicant also renews all previous arguments, particularly those filed November 1, 2007, and respectfully traverses the prior characterizations of the relevance of the prior references.

The Applicant points out that the present invention must be understood as being directed to a new type of architecture. That architecture is not shown or disclosed in any of the cited patents in combination. The claimed architecture may be considered to be of the class of the so-called Harvard structure. The cited art is all of the so-called von Neumann architecture. (Juvinal explicitly states that it is of the von Neumann model.) Chin is a set of von Neumann machines that are networked in such a way to maintain inter processor synchronization, or so it is asserted. Therefore, Juvinal and Chin do not lend themselves to any obvious combination, and certainly not a combination that points to the claimed invention.

The subject matter of Juvinal, which was specifically cited by the Applicant, is the type of prior art with deficiencies that the present invention addresses and overcomes, as discussed in the background of the invention. None of the art of record discloses computational structures or processing: 1) on a per-frame basis with one processor per pixel, in combination with 2) N-way symmetric multi-processing image processing at the object level that is in combination real-time capable.

In the Specification, the Applicant previously addressed the deficiencies of the prior art, to which Juvinal and Chin belong and represent. Key features are not disclosed or taught: First, processing of data at the pixel level (one processor per pixel) on a per-frame basis in a real-time physical environment and, second, processing of data at the object level with an SMP in a real-time physical environment, with all the constraints imposed by real-time processing. This is a fundamental and economically significant difference between this and the teachings of the prior art.

The deficiencies in the teachings of each of the references are herewith addressed.

1. The Examiner contended that Juvinall discloses that the pixel processor array receives image data as a full frame and processes it as such. That is not true. The Juvinall system reads the frame data into frame memory, and then the pixel processor array reads them block by block (or block-parallel, depending on how many pixel processors are available), and then the pixel processor processes the blocks such that pixels are processed sequentially within a block. There are a number of fundamental differences between Juvinall and the claimed invention. The claimed invention uses one processor per pixel, even if the frame data is multiplexed. Juvinall uses blocks. Juvinall describes a 1-bit processor. The present invention has a processor per pixel that uses as many bits as there are in the color representation, typically 8 bits per color or at least 24 bits per processor. By its nature, the claimed invention can and does traverse block boundaries for multiplexed frames. Traversal of block boundaries is not mentioned in Juvinall, nor is it required by the process described. Juvinall's MPP SIMD systolic array is based on a multitude of traditional CPUs, with I/O and external memory, each requiring and relying on common DRAM access for code and image data as well as for swap and temporary data. Specifically, Juvinall describes the processing of image data such that data is streamed into DRAM of the system, and then this frame data is fetched from DRAM block by block into the block RAM within the plurality of pixel processors, and is transferred back from there to DRAM (to complete the frame data), and only then from there into the next layer.

In the present invention, the architecture is such as to allow real-time streaming the data from an image sensor or a camera into the first layer processor array, and from there directly into the second layer processor within the constraints of real-time processing. A frame buffer between the camera and the first layer processor only needs to be deployed in this architecture if the entire frame is comprised of multiple frames from multiple cameras, or if realignment of frame data is required because the data is streamed in via unsynchronized high speed serial links from a high-speed camera (a camera with 10,000 frames per second or more).

2. Juvinall does not teach that the second layer processing is carried out in an SMP. In fact, Juvinall suggests the second layer processor array to be another MPP SIMD.

3. The Examiner then states that Chin discloses an N-way SMP system to perform the second layer processing. Chen does not disclose an N-way symmetric multi processor system. The assertion is evidently a hindsight reconstruction based on the Applicant's claim – it is certainly not found in Chin's disclosure. Chin very explicitly refers to an MPP SIMD and thus cannot be said to read on the claimed second layer.

It is a major change and not a clarification of the post-processing engine to change architecture from an MPP SIMD to a real-time capable SMP. Moreover, the MPP SIMD architecture herein claimed is not at all conventional.

In summary, it is also not obvious to one skilled in the art to use an MPP SIMD in the object independent first layer of image processing and an SMP for the object dependent second layer of processing and then third layer processing.

CONCLUSION

In view of the foregoing, Applicants believe all claims now pending in this Application are in condition for allowance and an action to that end is respectfully requested.

If the Examiner believes a telephone conference would expedite prosecution of this application, please telephone the undersigned at (650) 326-2400.

Respectfully submitted,



Kenneth R. Allen
Reg. No. 27,301

TOWNSEND and TOWNSEND and CREW LLP
Two Embarcadero Center, Eighth Floor
San Francisco, California 94111-3834
Tel: (650) 326-2400
Fax: (650) 326-2422
KRA:deh
61276555 v1